

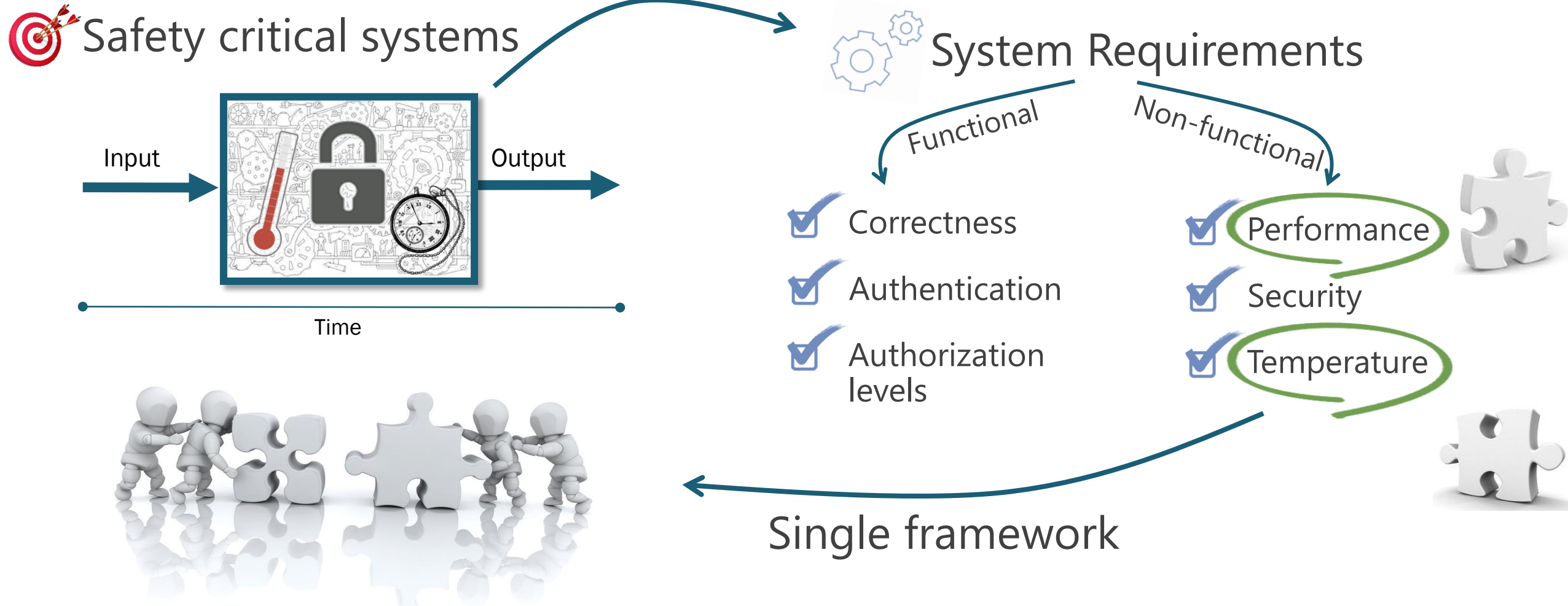
Thermal-Aware Schedulability Analysis for Fixed-Priority Non-Preemptive Real-Time Systems

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Real-Time & Embedded Computing Systems

Motivation



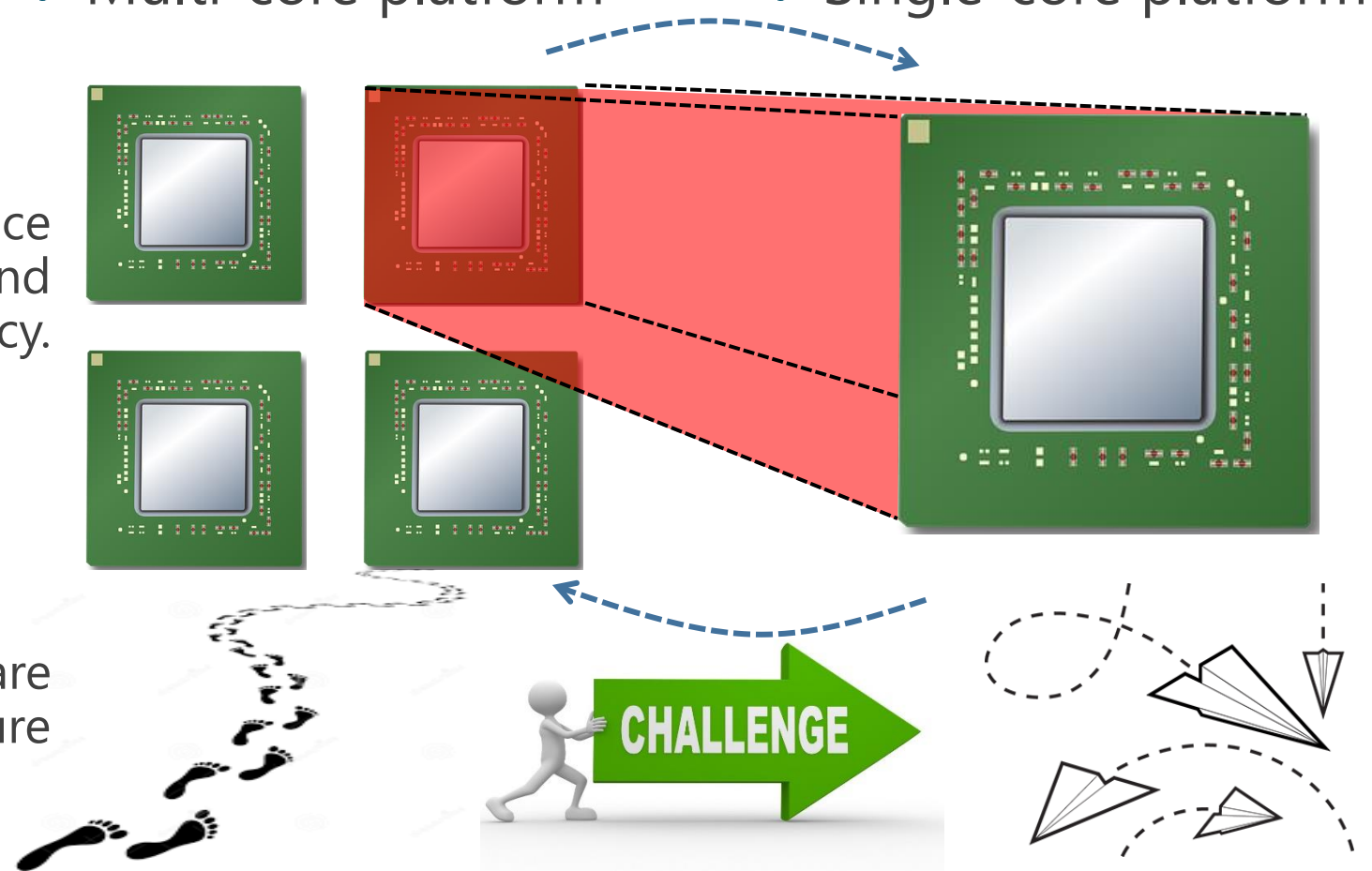
Research context

Safety critical systems

- ? Lack of formal policy and/or guidance by Federal Aviation Administration and European Union Aviation Safety Agency.
- ? Inherent non-deterministic behavior
 - ? Safety
 - ? Performance
 - ? Integrity
- ? Detailed technical information are available only under non-disclosure agreements.

> Multi-core platform

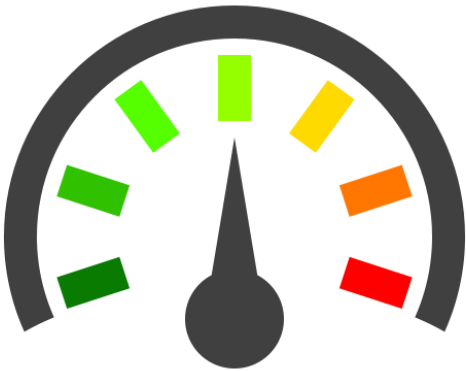
> Single-core platform



Existing strategies

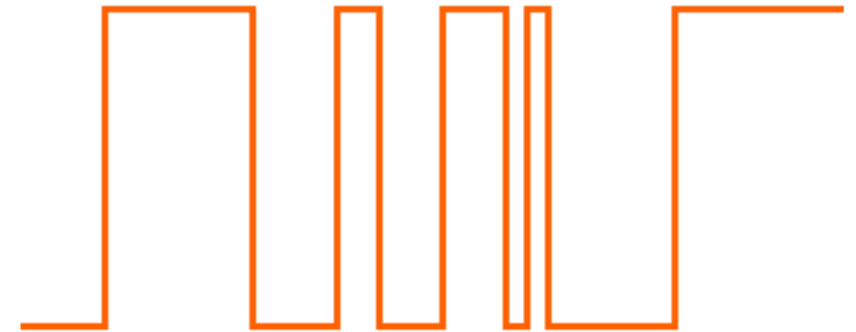
Dynamic Voltage/Frequency Scaling (DVFS)

- Discrete and limited number of frequencies
- Longer cooling periods
- Not available on all devices



Fetch Toggling (*global clock gating*)

- Smaller cooling periods
- Available on all devices

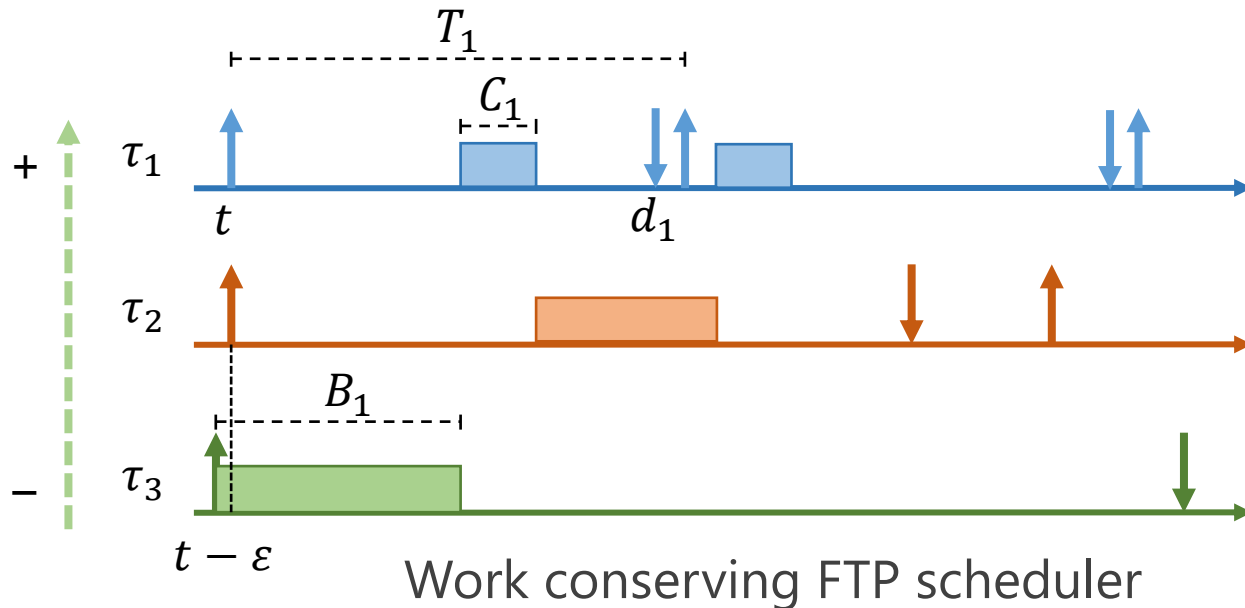


Task model



- Independent and periodic tasks: $\tau_i = (O_i, C_i, D_i, T_i)$
- Constrained deadline: $D_i \leq T_i, \forall i$
- Non-preemptive
- Same thermal profile

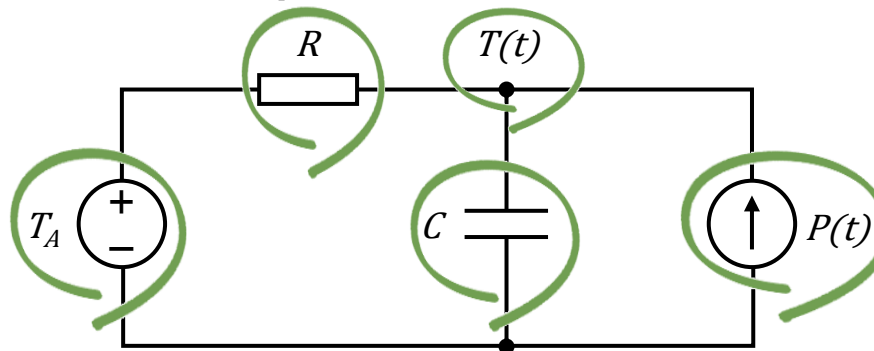
- ➖ Introduce additional blocking time in higher priority tasks.
- ➕ Naturally guarantees mutual exclusion and exclusive access to shared resources.
- ➕ Cheap to implement.
- ➕ Limited run-time overhead.



Thermal model



➤ HotSpot [1]

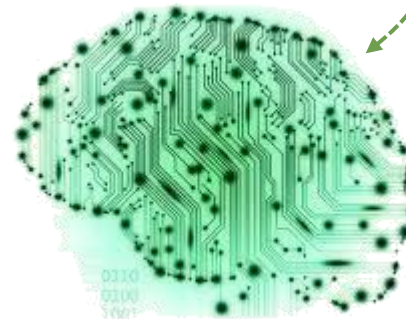


Constant ambient temperature

$$\frac{dT(t)}{dt} = \frac{P(t)}{C} - \frac{T(t) - T_A}{R \cdot C}$$

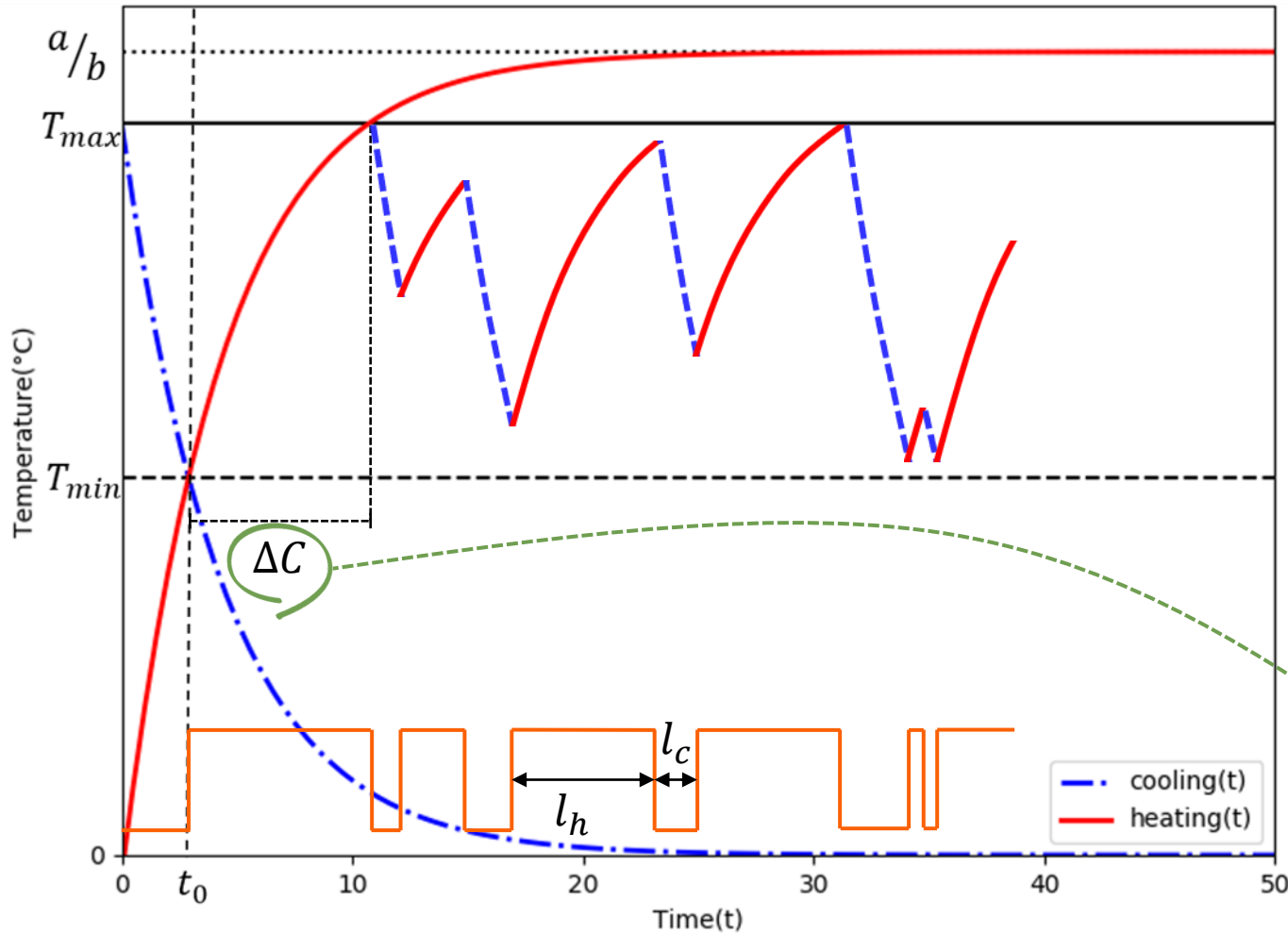
$$P(t) = P_D(t) + P_L(t)$$

- RC serial circuit
- Fine-grained
- Block-level



[1] K. Skadron, M. R. Stan, W. Huang, S. Velusamy, K. Sankaranarayanan, and D. Tarjan, "Temperature-aware microarchitecture: Extended discussion and results," in *Proceedings of the 30th Annual Int. Symposium on Computer Architecture*, 2003, pp. 2–13.

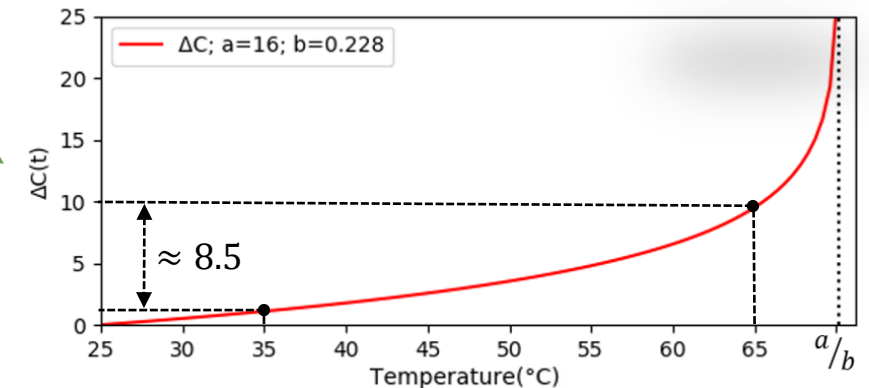
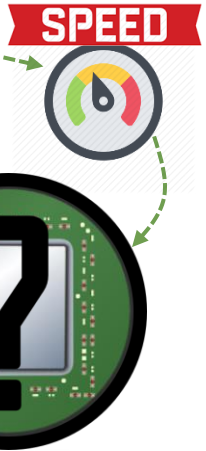
Thermal behavior



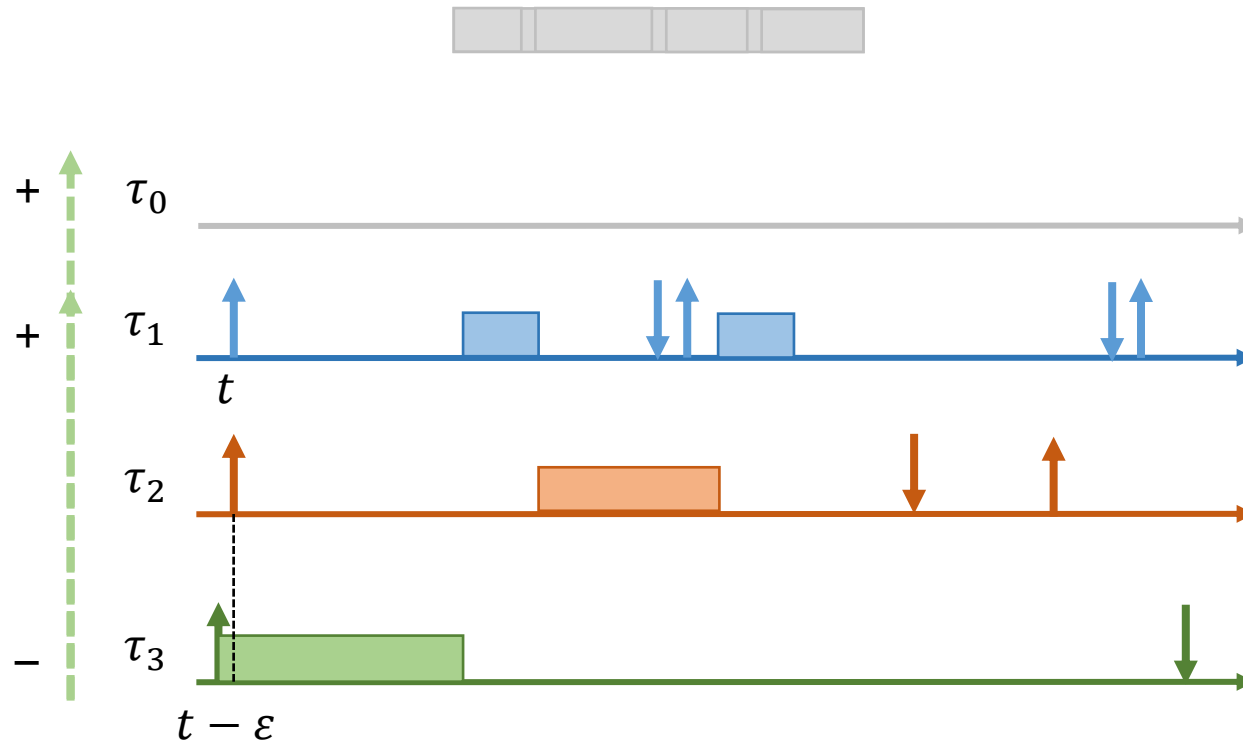
$$\frac{dT(t)}{dt} = \frac{P(t)}{C} - \frac{T(t) - T_A}{R \cdot C}$$

$$T_h(t) = \frac{a}{b} + \left(T(t_0) - \frac{a}{b} \right) \cdot e^{-b \cdot (t-t_0)}$$

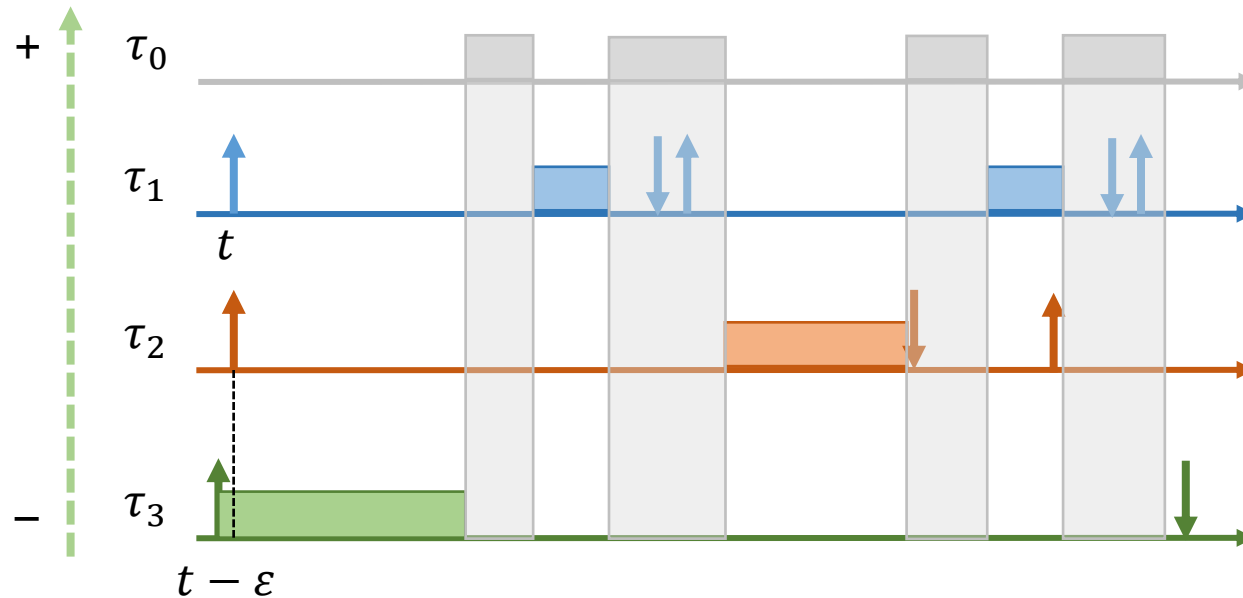
$$T_c(t) = T(t_0) \cdot e^{-b \cdot (t-t_0)}$$



Naive solution for cooling phases



Naive solution for cooling phases

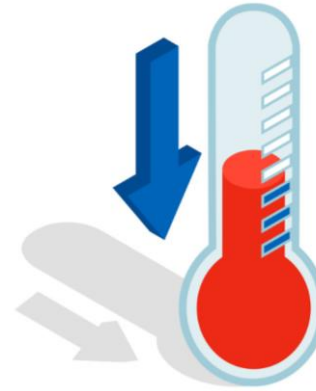


Periodic or aperiodic?
How frequent?
Where?
Which size?



Our contributions

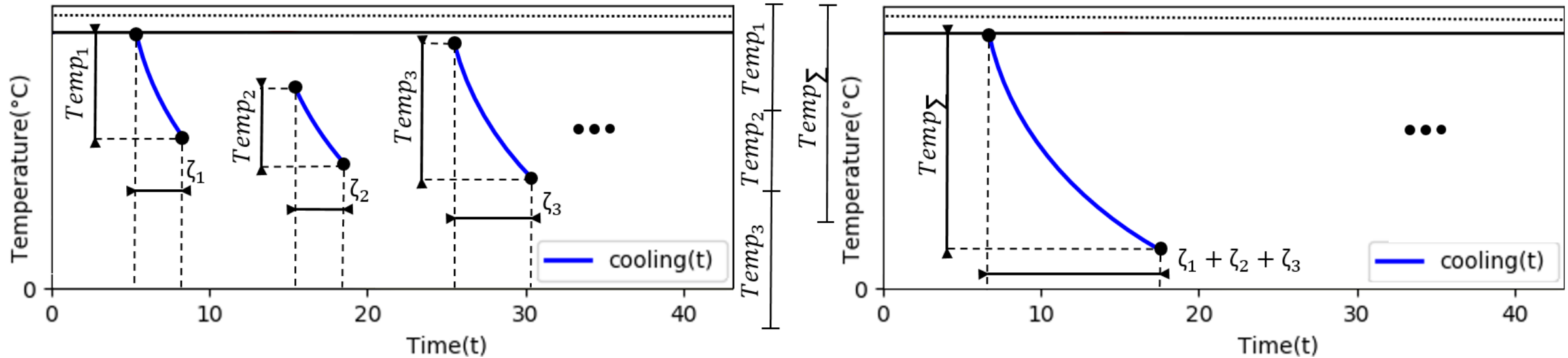
- Reactive scheduler: NP-HBC
 - Target low average temperatures



- Proactive scheduler: NP-CBH
 - Target high performances

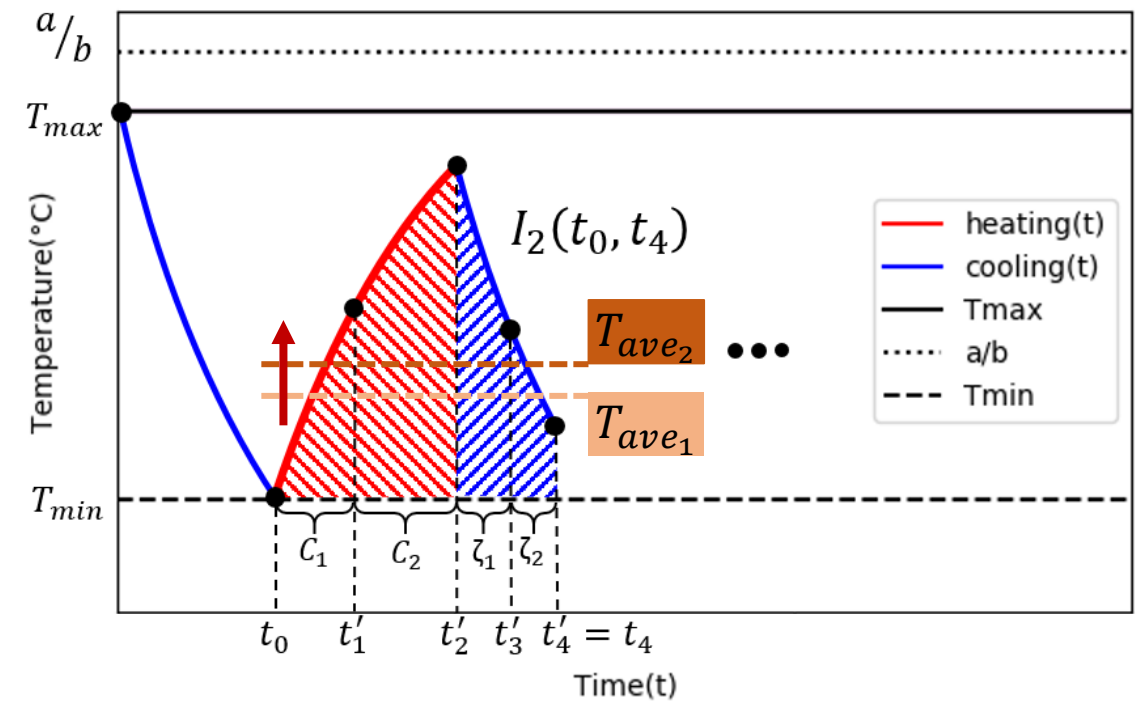
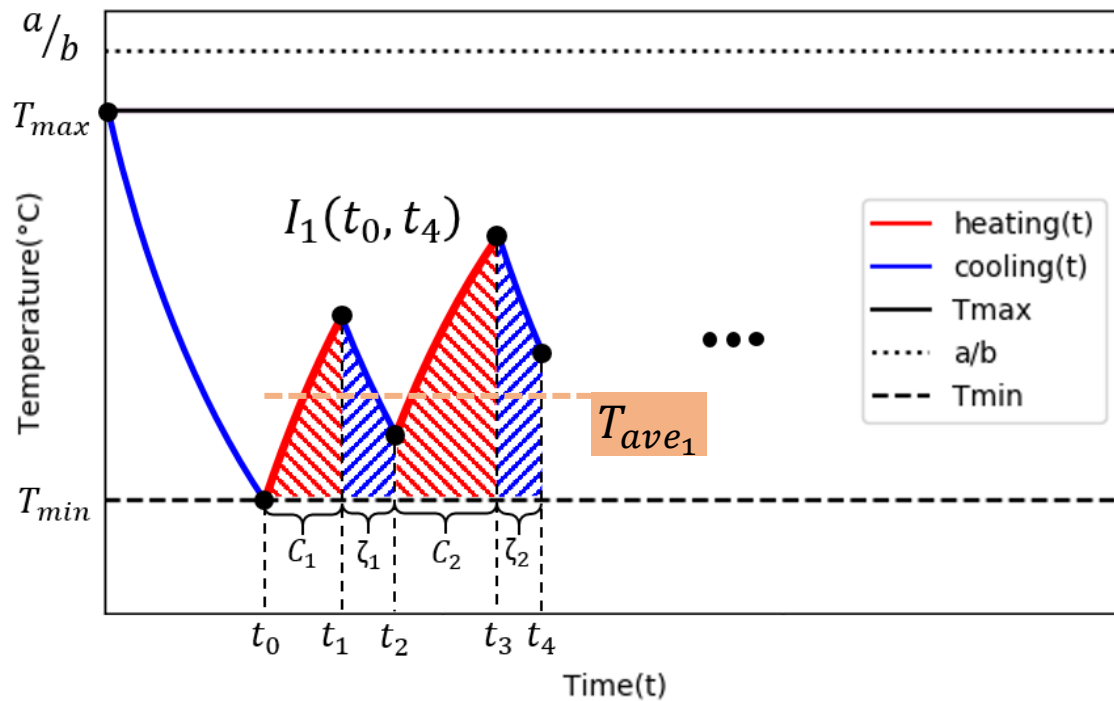


Cooling property

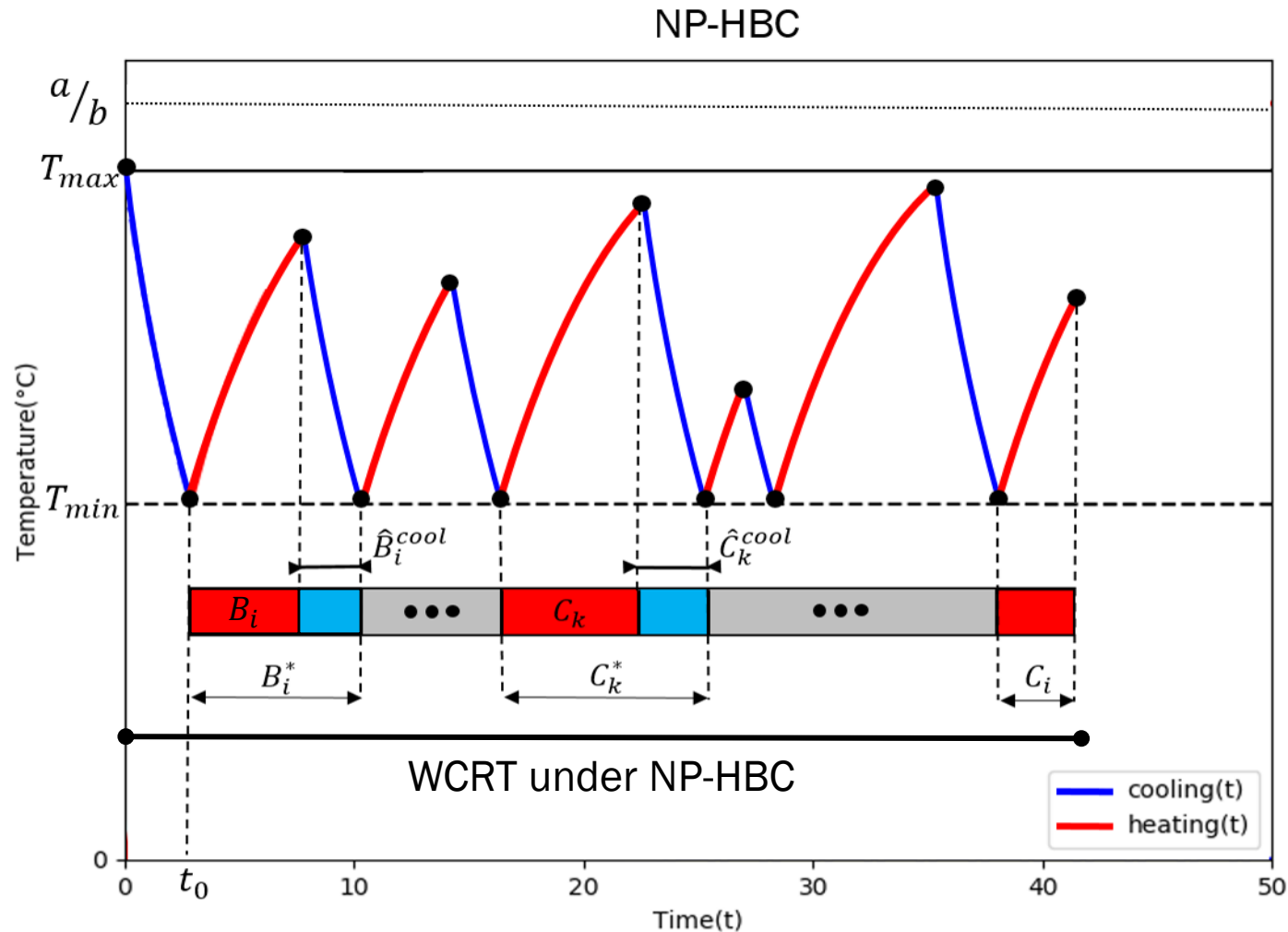


$$\sum_{j=1}^k T(\zeta_j) \geq T_c \left(\sum_{j=1}^k \zeta_j \right)$$

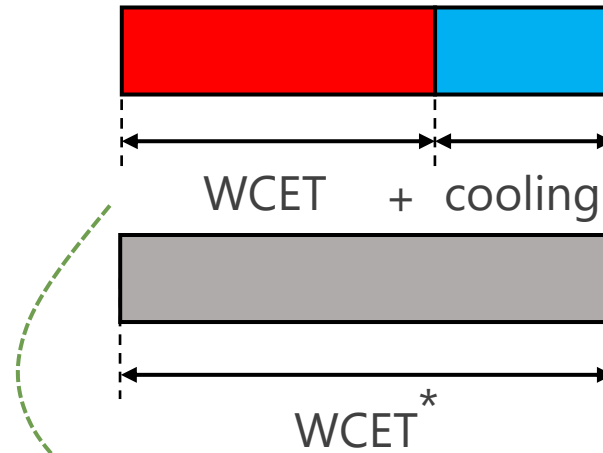
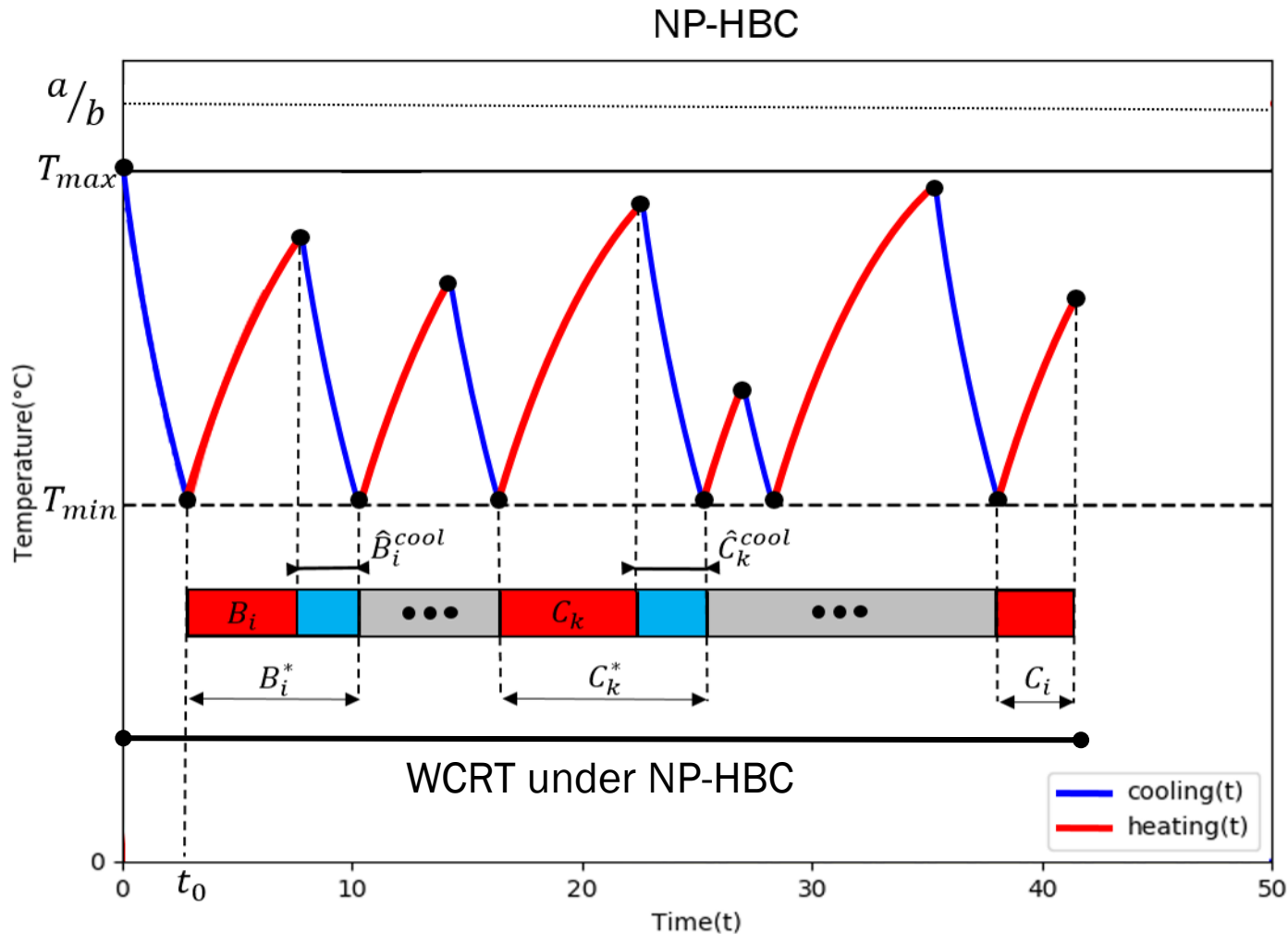
Average temperature reduction



Reactive scheduler: NP-HBC (1/2)



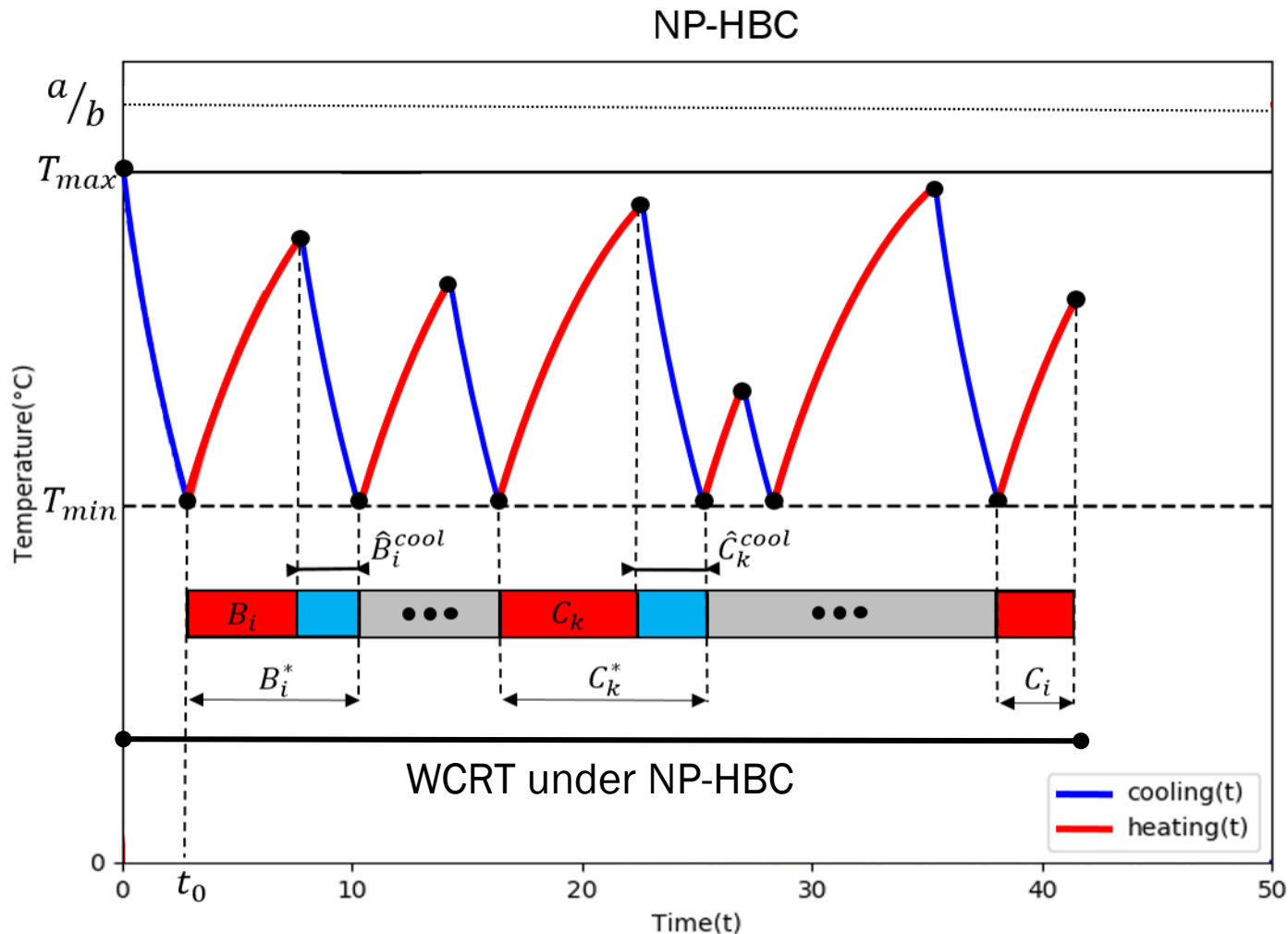
Reactive scheduler: NP-HBC (1/2)



Extends the classical scheduling theory

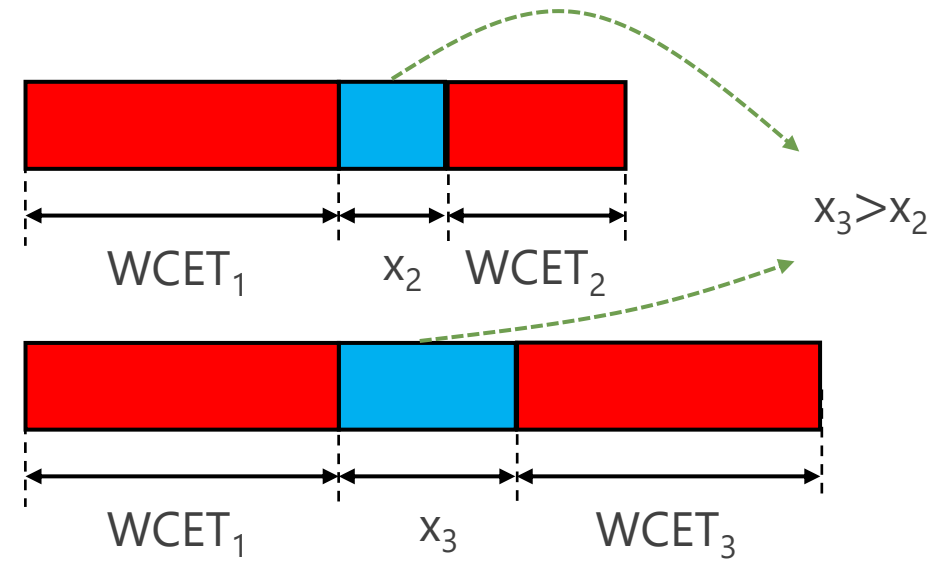
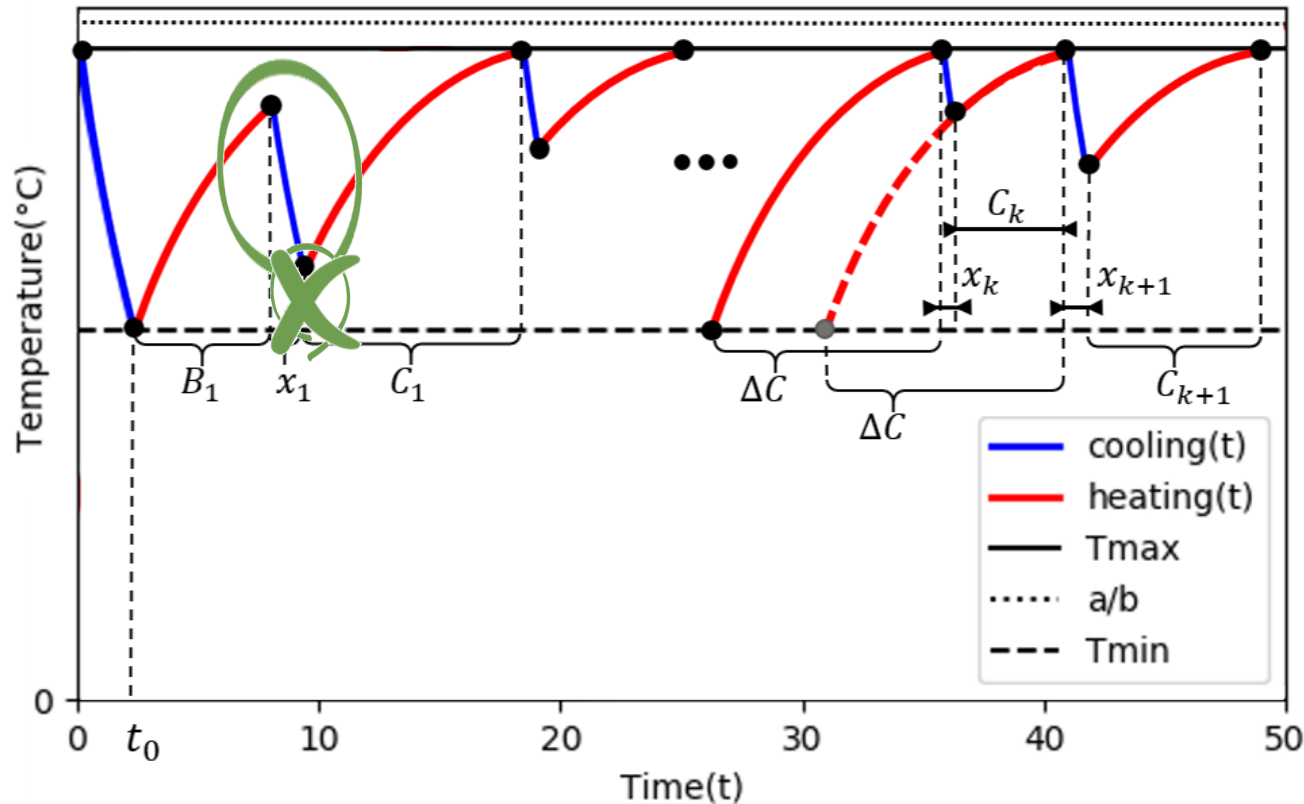


Reactive scheduler: NP-HBC (2/2)



- + Intuitive
- + Easy to implement
- + Closed-form equation
- + Agnostic to the priority assignment scheme
- Pessimism in the cooling time
- Pessimism in the response time

Proactive scheduler: NP-CBH (1/3)



$\tau_1: WCET_1$

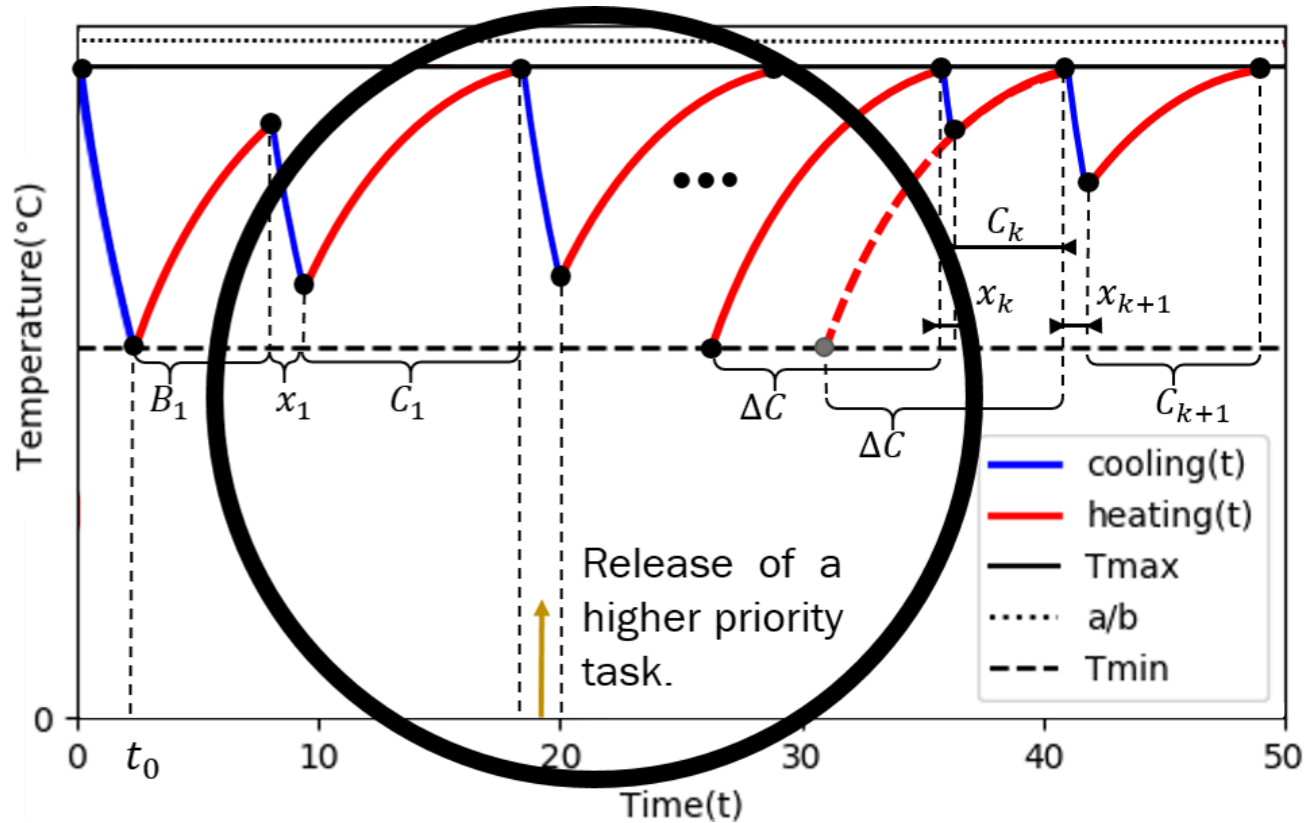
$\tau_2: WCET_2$

$\tau_3: WCET_3$

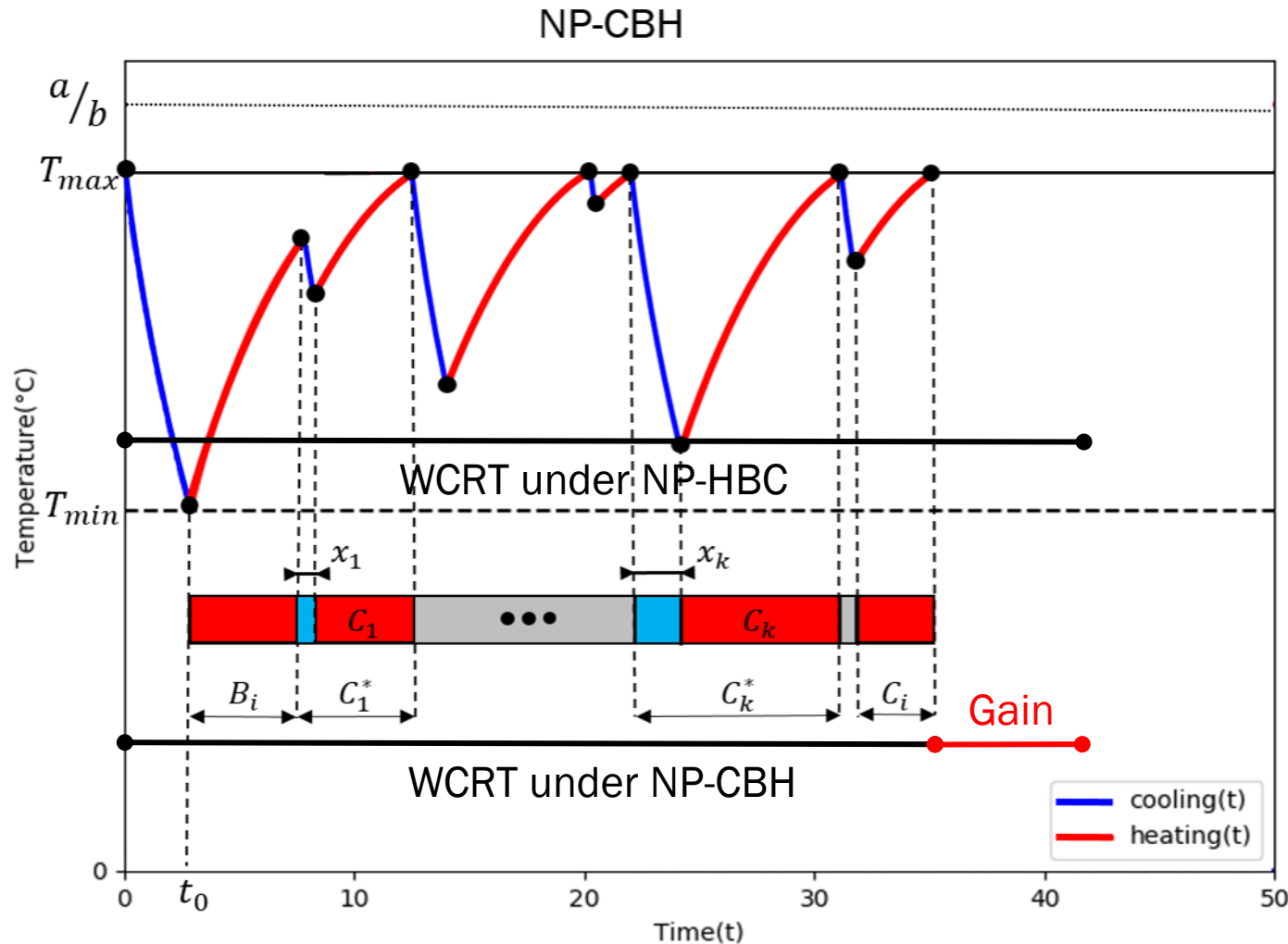
$WCET_3 > WCET_2$



Proactive scheduler: NP-CBH (2/3)



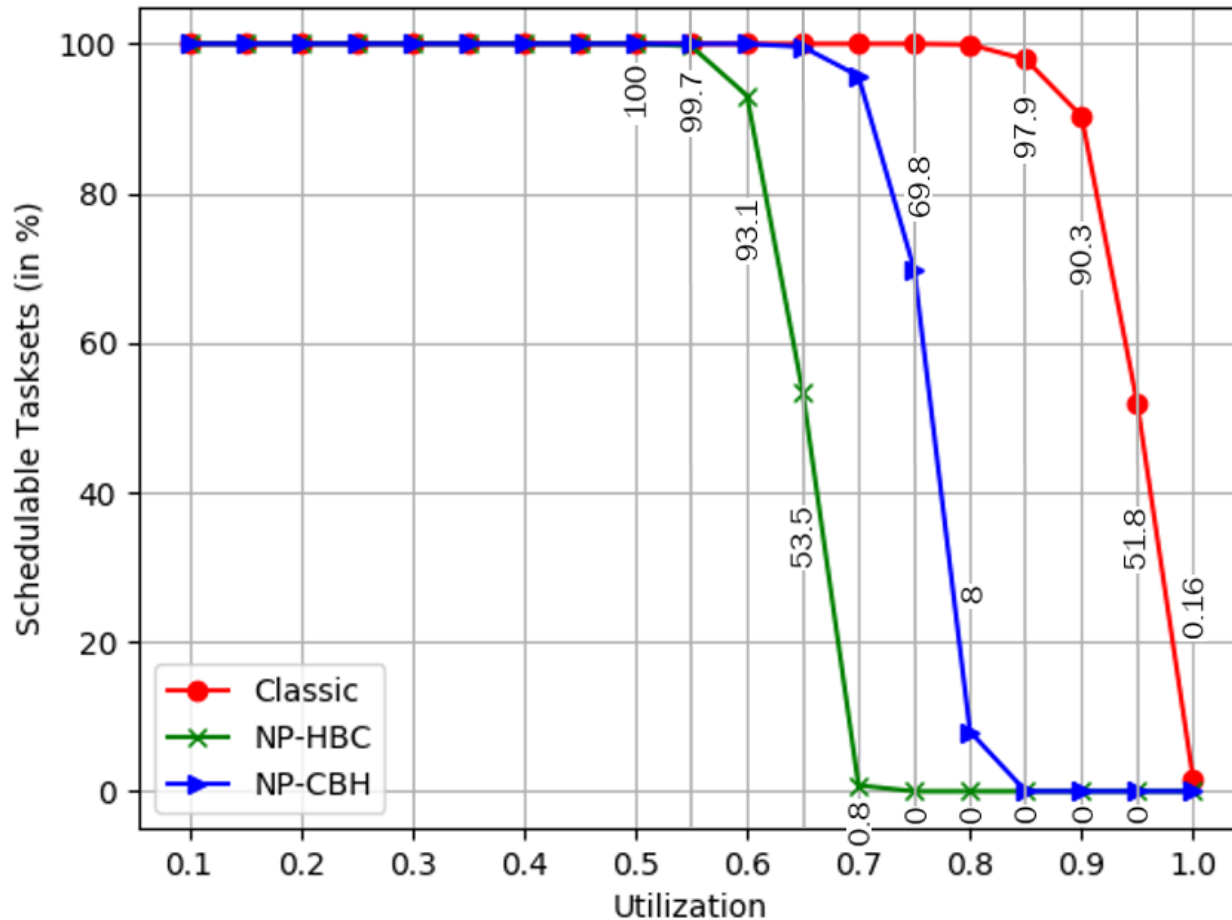
Proactive scheduler: NP-CBH (3/3)



- + More accurate cooling time
- + More accurate response time
- Complex to implement
- Task priority matters

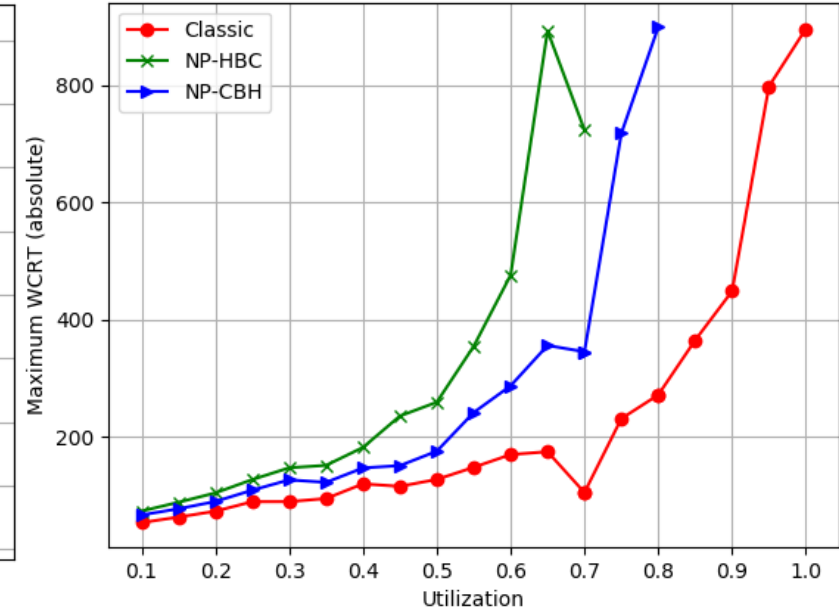
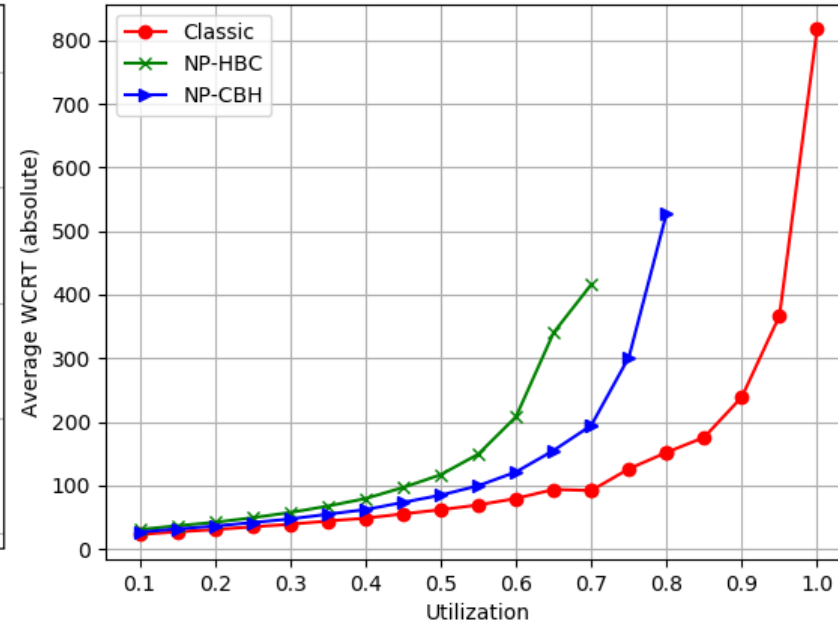
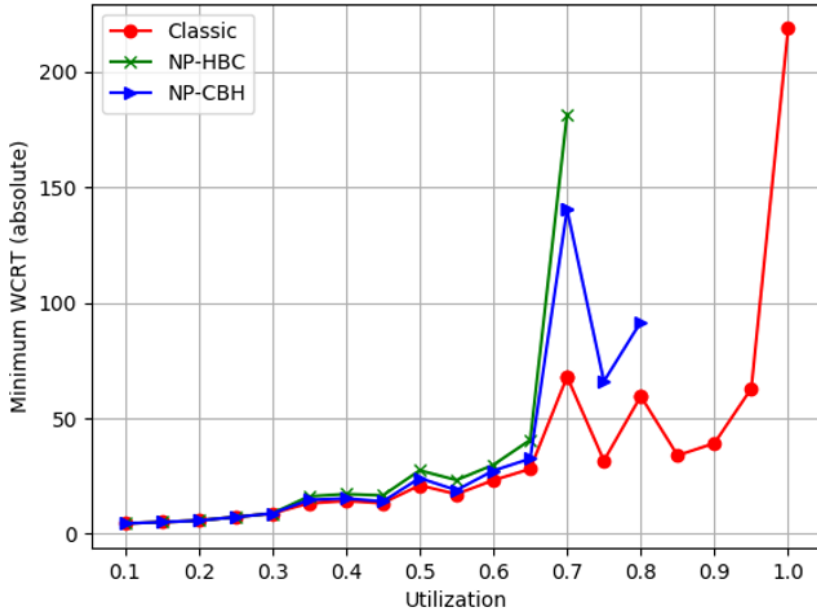


Results (1/2)



- 1000 task set per utilization:
 - Implicit deadline
 - Priority assignment: Rate Monotonic
- $a = 16$; $b = 0.228$ (silicon chip [1])
- $T_{max} = 65^{\circ}\text{C}$, $T_{min} = 30^{\circ}\text{C}$

Results (2/2)



Conclusion and future work



- Captured both the thermal and timing behaviors of the system in a single framework.
- Proposed two thermal-aware schedulers together with their schedulability analysis.
- Validated the run-time behavior of our solutions through intensive simulations.
- Future work:
 - How to extend the framework to DVFS-enabled platforms?
 - How to get around the priority assignment problem?
 - How to safely move to multi-cores?



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